HighProTech



Electric Actuator

HA500...suitable for valve stroke ≤20m, nominal output force 500N

Product Features

RS485 Remote Control

The actuator is equipped with RS485 communication interface. The valve can be remotely controlled by ModBus protocol.

Stroke Test Function

It can automatically measure the max. valve stroke without debugging.

Manual Device

The actuator has the mechanical manual function for easy maintenance and debugging.

Supporting APP

Supporting APP is offered to control the valve opening, set and read a number of parameters.

Speed Adjustability

The speed can be switched through Dip switch.

Seamless Connection

It adopts the seamless connection structure. It can ensure there is no gap during the movement which let the actuator have a higher control precision. The structure is simple and convenient to operate without tools.



Electric Actuator

HA600..., suitable for valve stroke \leq 20m, nominal output force 600N HA1000..., suitable for valve stroke \leq 20m, nominal output force 1000N HA1001..., suitable for valve stroke \leq 40m, nominal output force 1000N HA3000..., suitable for valve stroke \leq 40m, nominal output force 3000N HA5000..., suitable for valve stroke \leq 60m, nominal output force 5000N

Product Features

RS485 Remote Control

The actuator is equipped with RS485 communication interface. The valve can be remotely controlled by ModBus protocol.

• Stroke Test Function

It can automatically measure the max. valve stroke without debugging.

Manual Device

The actuator has the mechanical manual function for easy maintenance and debugging.

• Local Mode (Electric manual function)

The actuator has local control function which can control the valve opening and closing by the buttons on the plate.

Supporting APP

Supporting APP is offered to control the valve opening, set and read a number of parameters.

Speed Adjustability

The speed can be switched through Dip switch.

Seamless Connection

It adopts the seamless connection structure. It can ensure there is no gap during the movement which let the actuator have a higher control precision. The structure is simple and convenient to operate without tools.

LED Indicating Light

There are LED indicating lights on the actuator cover which is convenient to observe the actuator running status.



Electric Actuator

HA16000..., suitable for valve stroke ${\leq}100\text{m},$ nominal output force 16000N

Product Features

RS485 Remote Control

The actuator is equipped with RS485 communication interface. The valve can be remotely controlled by ModBus protocol.

• Stroke Test Function

It can automatically measure the max. valve stroke without debugging.

Manual Device

The actuator has the mechanical manual function for easy maintenance and debugging.

• Local Mode (Electric manual function)

The actuator has local control function which can control the valve opening and closing by the buttons on the plate.

Supporting APP

Supporting APP is offered to control the valve opening, set and read a number of parameters.

• Optional control/feedback signals

Four kinds of signals (0-10V, 2-10V, 0-20mA, 4-20mA) are optional. It can be selected via Dip switch.

• More reliable connection structure

The connection between actuator and valve stem adopts high strength connection mechanism to ensure the stability and avoid slippage.

♦ LED Indicating Light

There are LED indicating lights on the actuator cover which is convenient to observe the actuator running status.

Type Overview

	Operating					Velo	city		Rec			
Force	Voltage	Туре	Control signal	Feedback signal	Stroke	High	Low	Power	Transformer			
									-		24VAC:10VA	30VA
	2414	HA500S-24M-10	0(2)~10VDc, 0(4)~20mA , Floating	0(2)~10VDc, 0(4)~20mA		2s/mm	4s/mm	24VDC:5VA	15VA			
500N	24 V	HA500S-24M485-10	0(2) 10VDz 0(4) 20mA BS485	0(2) 10VDs 0(4) 20mA BS485	26mm	2e/mm	As/mm	24VAC:10VA	30VA			
		11A5003-24M485-10	0(2)~10 VDC, 0(4)~2011A, K3485	0(2)~10VDC, 0(4)~2011A, K3485		25/1111	45/1111	24VDC:5VA	15VA			
	220V	HA500S-220MF2-10	Floating	2 SPDT feedback		2s/1	nm	15VA	/			
		HA600S-24M-12	0(2)~10VDC, 0(4)~20mA, Floating	0(2) = 10 VDC $0(4) = 20$ m A		1c/mm	2s/mm	24VAC:33VA	50VA			
		1110000 2 111 12		0(2)-10 V DC,0(4)-2011A		1s/min	28/1111	24VDC:12VA	30VA			
	24V	HA600S-24M485-12	0(2)~10VDC, 0(4)~20mA, RS485	0(2)~10VDc, 0(4)~20mA, RS485		1s/mm	2s/mm	24VAC:33VA	50VA			
								24VDC:12VA	30VA			
600N		HA600S-24MF2-12	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA 2 SPDT feedback	30mm	30mm 1s/mm	2s/mm	24VAC:33VA	20VA			
		HA600S-220M-12	0(2)~10VDC_0(4)~20mA_Eloating	0(2) 10VDC 0(4) 20m A	-	1e/mm	20/mm	30VA				
		HA (000 220 MAS 12	0(2) 10VDC, 0(4) 20m A DC485	0(2)~10VDC,0(4)~20IIIA	-	1	23/1111	201/4	/			
	220V	HA600S-220M485-12	0(2)~10VDC, 0(4)~20mA, KS485	0(2)~10VDc, 0(4)~20mA, KS485	-	1s/mm	2s/mm	30VA	/			
		HA600S-220MF2-12	0(2)~10VDC, 0(4)~20mA Floating	0(2)~10VDC, 0(4)~20mA 2 SPDT feedback		1s/mm	2s/mm	30VA	/			
								24VAC:33VA	50VA			
		HA1000S-24M-12	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA		1s/mm	2s/mm	24VDC:12VA	30VA			
	241	114 10005 241495 12	0(2), 10VDC 0(4), 20mA PS485	0(2), 10VDa 0(4), 20mA BS485	1	1-/	20/mm	24VAC:33VA	50VA			
	24 V	HA10003-24M483-12	0(2)~10 VDC, 0(4)~2011A, K5485	0(2)~10VDC, 0(4)~2011A, K3485		15/1111	28/1111	24VDC:12VA	30VA			
1000N		HA1000S-24MF2-12	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA	30mm	1s/mm	2s/mm	24VAC:33VA	50VA			
10001				2 SPDT feedback	John			24VDC:12VA	30VA			
		HA1000S-220M-12	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA	-	1s/mm	2s/mm	30VA	/			
	220V	HA1000S-220M485-12	0(2)~10VDC, 0(4)~20mA, RS485	0(2)~10VDc, 0(4)~20mA, RS485		1s/mm	2s/mm	30VA	/			
		HA1000S-220MF2-12	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA		1s/mm	2s/mm	30VA	/			
				2 SPD1 Teedback				24VAC-22VA	501/4			
	24V	HA1000L-24M-14	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA		1s/mm	2s/mm	24VAC:55VA	30VA			
		HA1000L-24M485-14	0(2)~10VDC, 0(4)~20mA, RS485					24VAC:33VA	50VA			
				0(2)~10VDc, 0(4)~20mA, RS485		1s/mm	2s/mm	24VDC:12VA	30VA			
			0(2) 10VDC 0(4) 20-4 Electron	0(2)~10VDC, 0(4)~20mA	-		20/000	24VAC:33VA	50VA			
1000N		HA1000L-24MF2-14	0(2)~10VDC, 0(4)~20mA, Floating	2 SPDT feedback	50mm	ls/mm	2s/mm	24VDC:12VA	30VA			
	220V	HA1000L-220M-14	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA	1	1s/mm	2s/mm	30VA	/			
		HA1000L-220M485-14	0(2)~10VDC, 0(4)~20mA, RS485	0(2)~10VDc, 0(4)~20mA, RS485	1	1s/mm	2s/mm	30VA	/			
				0(2)~10VDC, 0(4)~20mA			2/	20174				
		HA1000L-220MF2-14	0(2)~10VDC, 0(4)~20mA, Floating	2 SPDT feedback		1s/mm	2s/mm	30VA	/			
	24V 220V	HA3000L-24M-14	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA		1s/mm 2s	2s/mm	24VAC:40VA	60VA			
					-			24VDC:20VA	50VA			
		24V	24V HA3000L-24M485-14	0(2)~10VDC, 0(4)~20mA, RS485	0(2)~10VDc, 0(4)~20mA, RS485		1s/mm 2s/m	2s/mm	24VAC:40VA	60VA		
									24VDC:20VA	50VA		
3000N		HA3000L-24MF2-14	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA 2 SPDT feedback	50mm ^{1s/m}	1s/mm	2s/mm	24VDC:20VA	50VA			
		HA3000L-220M-14	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA		1s/mm	2s/mm	50VA	/			
		HA3000L-220M485-14	0(2)~10VDC, 0(4)~20mA, RS485	0(2)~10VDc. 0(4)~20mA. RS485		1s/mm	2s/mm	50VA	,			
			•(-) ••••==,•(-) =•••	0(2) 10VDC 0(4) 20mA					/			
		HA3000L-220MF2-14	0(2)~10VDC, 0(4)~20mA, Floating	2 SPDT feedback		1s/mm	2s/mm	50VA	/			
	24V	HA5000L 24M 14	$0(2) \sim 10$ VDCC $0(4) \sim 20$ mA Floating	0(2), 10 VDC $0(4), 20$ m A		2s/mm 4	Ac/mm	24VAC:50VA	80VA			
		HA3000E-24W-14	0(2) 10 (Dee, 0(1) 20min, 1 loading	0(2)~10VDC, 0(4)~20mA			48/1111	24VDC:25VA	50VA			
5000N		HA5000L-24M485-14	0(2)~10VDC, 0(4)~20mA, RS485	0(2)~10VDc 0(4)~20mA RS485		2s/mm	4s/mm	24VAC:50VA	80VA			
			0(2)-10 VDC, 0(4)-2011A, R5405				-13/11111	24VDC:25VA	50VA			
		HA5000L-24MF2-14	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA	70mm	2s/mm	4s/mm	24VAC:50VA	80VA			
	220V	11450001-22014-14	0(2) 10VDC 0(4) 20m A Plant	0(2) 10VDC 0(4) 20 4	-	2.4	4	24VDC:25VA	50VA			
		HA5000L-220M-14	0(2)~10 v DC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA	-	2s/mm	4s/mm	60VA				
		HA5000L-220M485-14	0(2)~10VDC, 0(4)~20mA ,RS485	0(2)~10VDc, 0(4)~20mA, RS485	-	2s/mm	4s/mm	60VA	/			
		HA5000L-220MF2-14	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA 2 SPDT feedback		2s/mm	4s/mm	60VA	/			
	-	HA16000L-220M-15	0(2)~10VDC. 0(4)~20mA Floating	0(2)~10VDC 0(4)~20m∆	23	2.70	/mm	150VA	1			
		HA160001 220M495 15	0(2)~10VDC 0(4)~20mA DS485	0(2)~10VDc 0(4)~20mA DS495	-	2.73	(mm	150VA	/			
16000N	220V	11A10000L-220M485-15	0(2)~10 v DC, 0(4)~20MA,KS485	0(2)~10 v DC, 0(4)~20MA, KS485	110mm	2./s		130VA	/			
		HA16000L-220MF2-15	0(2)~10VDC, 0(4)~20mA, Floating	0(2)~10VDC, 0(4)~20mA 2 SPDT feedback		2.7s	'mm	150VA	/			

DIP Switch Instruction

Switch	Function	Description	
S1-1	Starting of control/ feedback signal	ON	4~20mA or 2~10VDC
		OFF	0~20mA or 0~10VDC
S1-2	Type of control signal	ON	Current signal
		OFF	voltage signal
S1-3	Input impedance	ON	voltage signal
515	input impedance	OFF	Current signal
S1-4	Type of control signal	ON	Current signal
51-4	Type of control signal	OFF	voltage signal
S1-5	Operating mode	ON	When the control signal increases, actuator shaft extends; When the control signal decreases, actuator shaft retracts.
		OFF	When the control signal increases, actuator shaft retracts; When the control signal decreases, actuator shaft extends.
S1-6	Losing control signal	ON	When lose control signal (voltage type or current type), actuator will provide a min. control signal internally.
		OFF	 When lose control signal (voltage type), actuator will provide a max. control signal internally. When lose control signal (current type), actuator will provide a min. control signal internally.
\$1.7	Self stroking mode	ON	Power on each time, self-stroking starts automatically.
51-7	Sen-subking mode	OFF	Self-stroking starts only when press the self-stroking button manually.
S1 9	Control type (when S1-9 is OFF)	ON	Floating
51-0		OFF	Modulating
\$1_9	Control mode	ON	RS485 interface control (Modbus protocol)
51-9	Control mode	OFF	Modulating and floating type
\$1-10	Velocity	ON	High
31-10	velocity	OFF	Low

Function Introduction

Modulating type

Control signal/feedback signal: 4~20mA ON OFF 3 4 5 6 7 8 9 10 1 2

Control signal/feedback signal: 0~10VDC



When TW...is modulating type, terminal B,O is power input, actuator can be controlled by connecting terminal O,E, as shown above, when equipped with our TL.../TE../TTF...series Globe Valve, DIP Switch S1-5 is DA mode: Control signal at terminal O,E increasing: actuator shaft extends, valve stem retracts, valve tends to open. Control signal at terminal O,E decreasing: actuator shaft retracts, valve stem extends, valve tends to close. Control signal at terminal O,E has no changing, actuator shaft and valve stem stay in present position.

When voltage (or current) signal is disconnected, this is equivalent to input a min. control signal, actuator shaft retracts, valve closed.

Floating Type



When Dip switch S1-8 is on, it is floating type. Terminal B,O is power input, control the actuator by the switch O,UP,DOWN:

O, UP connected: actuator shaft retracts, and valve stem extends O, DOWN connected: actuator shaft extends, and valve stem retracts

Notes: Terminal E,Y doesn't work by this time!

RS485 Bus Communication



When Dip switch S1-9 is on, it is RS485 Bus communication type. Terminal B,O is power input, remote control by terminal 8,9:

Actuator can be controlled remotely by RS485 bus communication, actuator supports ModBus protocol. Notes: Terminal O,E,Y,UP,DOWN doesn't work by this time!

HighProTech

Wiring (HA500...)

• HA500S-24M-10



HA500S-220M-10



• HA500S-24(220)M485-10



• HA500S-220MF2-10



Notes:

Terminal 1, 2, and 3 are power input:

When terminal 1 and 2 power on, the actuator will run from 1 to 0.

When terminal 1 and 3 power on, the actuator will run from 0 to 1.

Terminal 4, 5, 6, and 7 are SPDT feedback:

When the actuator runs to limiting position 0, terminal 4 and 5 will conduct and output dry contact feedback.

When the actuator runs to limiting position 1, terminal 6 and 7 will conduct and output dry contact feedback.

HighProTech

Wiring (HA600/1000/1001/3000/5000/16000...)

• HA600/1000/1001/3000/5000-24M...



• HA600/1000/1001/3000/5000/16000-220M...



• HA600/1000/1001/3000/5000-...M485...



• HA600/1000/1001/3000/5000-... MF2...



Wiring Instruction

1. Please cut off power supply during wiring in order to ensure personal safety!

2. Carefully check the power voltage when wiring, wire according to the product parameter, if not, it may cause fire and endanger personal safety in severe case!



Indicating Light

• HA500...



Reset	Status	Description	
Green	Always	Normal mode	
Orange	Flashing	Self-stroking	
Red	Quick flashing	Alarming	

• HA600/1000/1001/3000/5000/16000...



UP	Status	Description
Green	Always	Normal mode
Red	Always	Local mode
Orange	Always	Reach upper limit posi- tion
Red	Flashing	Alarming

Reset Status		Description
Green	Always	Normal mode
Red Always		Local mode
Orange	Flashing	Self-stroking
Red Ouick flashing		Alarming

DOWN	Status	Description
Green	Always	Normal mode
Red	Always	Local mode
Orange	Always	Reach lower limit position
Red	Flashing	Alarming

Debugging Instruction

A. Connect actuator and valve body, wiring according to wiring diagram.

B. Automatic self-stroking (factory default setting): actuator will repeat automatic self-stroking when power on each time, the process is as follows:

1) The Reset yellow indicating light will keep flashing, actuator shaft extends to lower limit position firstly and then, it retracts to upper limit position, actuator will not be controlled by signal by this time.

2) Reset yellow light stop flashing, self-stroking stops. By then, actuator running direction can be controlled by control signal.

3) If the Reset red light is quick flashing during the self-stroking, it means the self-stroking status is not correct and the actuator will start alarming. The actuator can not match with the valve's max. stroke.

Remarks: If you don't need automatic self-stroking function , you can set the 7th switch to OFF, it will change into manual self-stroking.

C. Manual self-stroking function: If self-stroking is need in a power-on state, press down the Reset button over 5 seconds, and then the actuator starts self-stroking. The phenomenon is the same as step B.

D. RS485 function:

RS485 adopts standard Modbus protocol, the following parameters can be set through supporting APP:

RS485 address: the default address is 1.

Band rate:2400/4800/9600(Default) /19200

Byte format: 8bit Data Bits, No Parity (Default)/odd check/even check, 1 stop bit

E. Cellphone supporting APP: Open the mobile APP client and close to the actuator scanning area. After connected, it can set the actuator parameters.

Notes:

Current type actuator can't set signal division, please use the function after setting voltage type.

3. Open the cover when wiring, prohibit disassembling other spare parts!

4. After wiring, please install the cover to the original position to avoid electric shock!

Assembling instruction







- 1. Shut off and prepare for manual operation.
- 2. Insert the Allen wrench into the manual hole on the top of the cover.
- 3. Turn the Allen wrench anticlockwise, the actuator shaft retracts; Turn it clockwise, the actuator shaft extends.
- 4. Manual operation is done, take out the wrench and cover tightly the red plug.

Note: In the case of power off, the actuator needs self-stroking again after the manual operation is completed.

Manual self-stroking method: press the Reset button on the actuator cover over 5s, actuator will enter self-stroking!

Dimension



HA16000...



w

HA600/1000/1001/3000/5000...

HA series	L mm	W mm	H mm
HA500	97	170	192
HA600	143	173	255
HA1000	143	173	255
HA1001	143	173	275
HA3000	143	193	285
HA5000	143	193	305
HA16000	232	292	583

HighProTech

Technical Parameters

• Operating Parameters				
Rated output power	500N / 600N / 1000N / 3000N / 5000N / 16000N			
Operating Voltage				
НА24М НА220М	24VAC±15%, 24VDC±15% 220VAC±15%			
Control sensibility	Modulating: 0.8% (For TW200: 1%) RS485: 0.3% (default setting)			
Dead zone (only for modulating type)	2% (default setting)			
Impedance (only for modulating type)				
voltage input impedance current input impedance	>100K <0.2K			
Load requirements (only for modulating type)				
voltage output load requirement current output load requirement	> 2K < 0.5K			
Degree of protection	HA500: IP54 HA600/1000/1001/3000/5000: IP65 HA16000: IP65			
Cable connector	PG13.5			
Life time	100 thousand cycles			

Spare Parts Material	
Cover	HA500: PC HA600/1000/1001/3000/5000: PC HA16000: Aluminum die casting
Body	HA500: PC HA600/1000/1001/3000/5000: Aluminum die casting HA16000: Aluminum die casting
Bracket	HA500: Aluminum die casting HA600/1000/1001/3000/5000: stainless steel HA16000: stainless steel
Seat	HA500: Aluminum die casting HA600/1000/1001/3000/5000: Aluminum die casting HA16000: casting iron

•	Environment Parameter				
Run	Running				
	Ambient temperature	-25~+65°C			
	Ambient humidity	≤95% RH non-condensation			
Storage					
	Ambient temperature	-40~+65°C			
	Ambient humidity	≤95% RH non-condensation			